

Solving Diffusion ODEs with Optimal Boundary Conditions

for Better Image Super-Resolution

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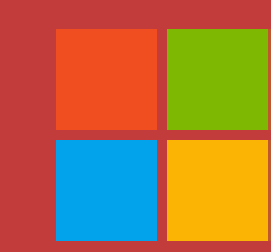
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Introduction

Problem:

Instability during inference of Diffusion-based SR models due to the randomness.

Existing Works:

Did not deal with the phenomenon.

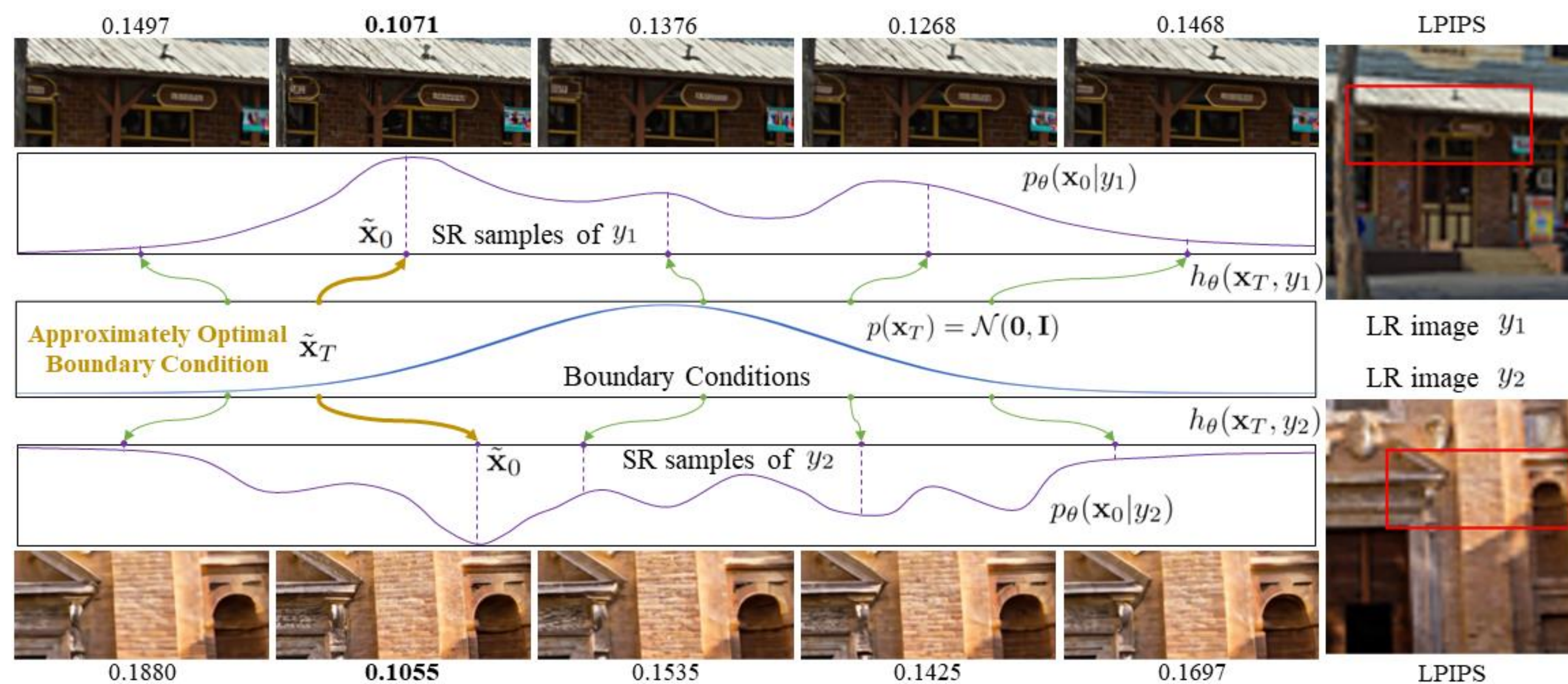
Simply fixed the random seed during inference.

Our Solution

Analysis on the **Approx. Optim. BC** of Diffusion ODEs.

Obtaining the $\tilde{\mathbf{x}}_T$ with a ref. set of image pairs.

Applying the $\tilde{\mathbf{x}}_T$ to all the LRs, achieving better and stable results.



Approach - Can Boost All the Diffusion-based SR Models

Preliminary: Diffusion ODE sampler

The results are determined by the **boundary condition** \mathbf{x}_T (i.e., the Gaussian noise at the start of the sampling process).

e.g., DDIM (ICLR 21'), DPM-Solver (NIPS 22').

Thus, the SR images can be a function of BC and LR image:

$$\mathbf{x}_0 = h_\theta(\mathbf{x}_T, \mathbf{y})$$

Find an Approx. Optim. BC $\tilde{\mathbf{x}}_T$

We employ perceptual distance between SR and HR as an approximated implementation of the likelihood.

We build a reference set and calculate the $\tilde{\mathbf{x}}_T$ on it:

$$\tilde{\mathbf{x}}_T \approx \arg \min_{\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})} \sum_{i=1}^R M(h_\theta(\mathbf{x}_T, \mathbf{y}_i), \mathbf{z}_i)$$

Optimal Boundary Condition \mathbf{x}_T^*

The BC that can generate the SR image which is the most close to the HR image:

$$\mathbf{x}_0^* = h_\theta(\mathbf{x}_T^*, \mathbf{y}), \text{ where } \mathbf{x}_0^* = \arg \max_{\mathbf{x}_0} p_\theta(\mathbf{x}_0 | \mathbf{y})$$

We prove that the \mathbf{x}_T^* is approximately consistent to different LRs:

$$\mathbf{x}_T^* = \arg \max_{\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})} p_\theta(h_\theta(\mathbf{x}_T, \mathbf{y})) \approx \arg \max_{\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})} p_\theta(h_\theta(\mathbf{x}_T, \mathbf{y}_i)), \forall \mathbf{y}_i \in \mathcal{C}$$

Apply the $\tilde{\mathbf{x}}_T$ to Different LRs

As we have declared before, the $\tilde{\mathbf{x}}_T$ can be directly applied in the sampling process of different LRs:

$$\tilde{\mathbf{x}}_0 = h_\theta(\tilde{\mathbf{x}}_T, \mathbf{y})$$

achieving stable and better SR performances.

The method does not limited the SR model itself, which means it can be employed in all the diffusion-based SR models.

Experiments

We evaluate our approach on 3 different diffusion-based SR models.

On Real World-SR

On Bicubic-SR

Model (& sampling method)	DISTS ↓	DIV2k-test			DISTS ↓	RealSR	
		LPIPS ↓	PSNR ↑	LPIPS ↓		PSNR ↑	
RealSR	0.3051	0.5148	22.52	0.2532	0.3673	26.30	
BSRGAN	0.2253	0.3416	22.13	0.2057	0.2582	25.52	
DASR	0.2340	0.3444	22.02	0.2113	0.3014	26.32	
Real-ESRGAN	0.2108	0.3109	22.36	0.2020	0.2511	25.12	
KDSR-GAN	0.2022	0.2840	22.92	0.2006	0.2425	26.09	
StableSR	DDPM-200	0.2010	0.3189	19.42	0.2210	0.3065	21.37
	DDIM-50	0.2217	0.3629	18.82	0.2336	0.3536	21.24
	DDIM-50 + $\tilde{\mathbf{x}}_T$	0.2046	0.3169	19.55	0.2164	0.2999	22.13
DiffIR	D-4	0.1773	0.2360	22.94	0.2076	0.2604	25.33
	D-4 + $\tilde{\mathbf{x}}_T$	0.1772	0.2357	22.95	0.1993	0.2419	25.82

Model (& sampling method)	DIV2k-test		Urban100		BSD100		
	LPIPS ↓	PSNR ↑	LPIPS ↓	PSNR ↑	LPIPS ↓	PSNR ↑	
ESRGAN	0.1082	28.18	0.1226	23.04	0.1579	23.65	
RankSRGAN	0.1171	27.98	0.1403	23.16	0.1714	23.80	
SRDiff	0.1286	28.96	0.1391	23.88	0.2046	24.17	
SR3	DDPM-1000	0.1075	28.75	0.1165	24.33	0.1555	23.86
	DDPM-250	0.1142	28.95	0.1181	24.41	0.1621	24.00
	DDPM-100	0.1257	29.16	0.1232	24.51	0.1703	24.15
	DPMS-20	0.1653	27.25	0.1413	23.46	0.2037	22.79
	DDIM-50	0.1483	28.55	0.1333	24.16	0.1823	23.75
	DDIM-100	0.1571	28.16	0.1335	24.05	0.1950	23.55
SR3 + $\tilde{\mathbf{x}}_T$	DPMS-20 + $\tilde{\mathbf{x}}_T$	0.1210	27.45	0.1179	23.57	0.1687	22.81
	DDIM-50 + $\tilde{\mathbf{x}}_T$	0.1053	28.65	0.1164	24.26	0.1552	23.99
	DDIM-100 + $\tilde{\mathbf{x}}_T$	0.1032	28.48	0.1136	24.12	0.1505	23.67

Visual Results

